Deterministic Finite Automata (DFA)

(LECTURE 3)

Introduction

- Finite automata and regular sets
- Definition of deterministic finite automata
- String accepted by DFA

Finite Automata and regular sets (languages)

• States and transitions:

Ex: Consider a counter data structure (system):

- unsigned integer counter: pc; { initially pc = 0}
- operations: inc, dec;
- ==> The instantaneous *state* of the system can be identified by the value of the counter. Operations called from outside world will cause *transitions* from states to states and hence change the current state of the system.

Problem: how to describe the system :

Mathematical approach: CS = (S, O, T, s, F) where

- S = The set of all possible states = N
- O = the set of all possible [types of] operations
- T = the response of the system on operations at all possible states. (present state, input operation) --> (next state)

Example of a state machine

T can be defined as follows : T: SxO --> S s.t., for all x in S ,

- $T(x, inc) = x + 1 and T(x, dec) = x 1; \{ 0 1 =_{def} 0 \}$
- s = 0 is the initial state of the system
- F ⊆ S is a set of distinguished states, each called a final state. (we can use it to, say, determine who can get a prize)
- Graphical representation of CS:
- Note: The system CS is infinite in the sense that S (the set of all possible states) and Transitions (the set of possible transitions) are infinite. A system consists of only finitely many states and transitions is called a *finite-state transition system*. The mathematical tools used to model finite-state transition system are called *finite automata*.
- examples of state-transition systems: electronic circuits; digital watches, cars, elevators, etc.

Deterministic Finite automata (the definition)

• a DFA is a structure M = (Q,S, d,s,F) where

- Q is a finite set; elements of S are called states
- S is a finite set called the input alphabet
- d:QxS --> Q is the transition function with the intention that if M is in state q and receive an input a, then it will move to state d(q,a).
 - e.g; in CS: d(3, inc) = 4 and d(3, dec) = 2.
- s in Q is the start state
- F is a subset of Q; elements of F are called accept or final states.
- To specify a finite automata, we must give all five parts (maybe in some other forms)
- Other possible representations:
 - [state] transition diagram or [state] transition table

Example and other representations

Ex 3.1: $M_1 = (Q, S, d, s, F)$ where

- $Q = \{0, 1, 2, 3\}, S = \{a, b\}, s = 0, F = \{3\} and d is defined by:$
- o d(0,a) = 1; d(1,a) = 2; d(2,a) = d(3,a) = 3 and
- o d(q,b) = q if $q = \{0,1,2,3\}$.

• problem: Although precise but tedious and not easy to understand (the behavior of) the machine. • >0 1 0

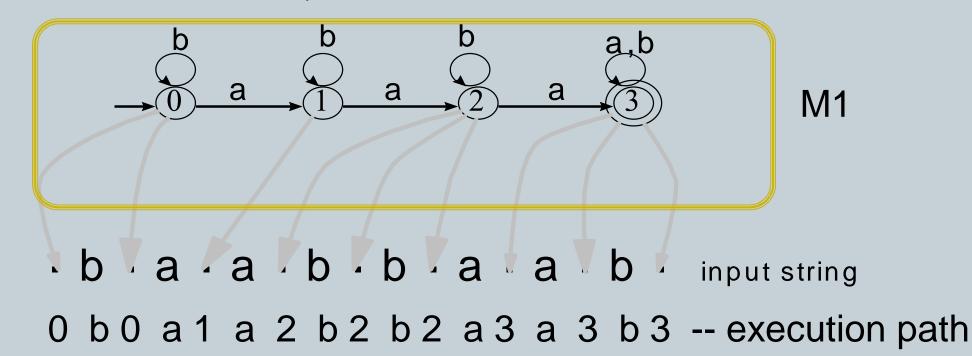
3F

• Represent M_1 by a table: ====> • Represent M_1 by a diagram: () • 0 a 1 a 2 a 3

state-transition diagram for M₁ note: the naming of states is not necessary

Strings accepted by DFAs

Operations of M₁ on the input 'baabbaab':



Since M₁ can reach a final state (3) after scanning all input symbols starting from initial state, we say the string 'baabbaab' is accepted by M₁.
 Problem: How to formally define the set of all strings accepted by a DFA ?

The extended transition function D

• Meaning of the transition function:

q1 - a - > q2 [or d(q1,a) = q2] means

if M is in state q1 and the currently scanned symbol (of the input strings is a) then

- 1. Move right one position on the input string (or remove the currently scanned input symbol)
- 2. go to state q2. [So M will be in state q2 after using up a)
- Now we extend d to a new function D: Q x S* --> Q with the intention that : D(q1,x) =q2 iff

starting from q1, after using up x the machine will be in state q2. --- D is a multi-step version of d.

Problem: Given a machine M, how to define D [according to d]?

Note: when string x is a symbol (i.e., |x| = 1) then D(q,x) = d(q,x).

for all state q, so we say D is an extension of d.

The extended transition function D (cont'd)

• D can be defined by induction on |x| as follows:

Basis: |x| = 0 (i.e., x = e) ==> D(q, e) = q --- (3.1)

- Inductive step: (assume D(q,x) has been defined) then
- D(q, xa) = d(D(q, x), a) --- (3.2)
- --- To reach the state D(q,xa) from q by using up xa, first use up x (and reach D(q,x)) and then go to d((D,qx),a) by using up a.
- Exercise: Show as expected that D(q,a) = d(q,a) for all a in S.

pf: D(q,a) = D(q,ea) = d(D(q,e),a) = d(q,a).

Uniqueness of the extended transition funciton

 Note: D is uniquely defined by M, i.e., for every DFA M, there is exactly one function f:QxS* --> Q satisfying property (3.1) and (3.2.)
 --- a direct result of the theorem of recursive definition.

pf: Assume \$ distinct f1 and f2 satisfy (3.1&3.2). Now let x be any string with least length s.t. $f1(q,x) \neq f2(q,x)$ for some state q.

$$==>1. x \neq e(why?)$$

2. If x = ya = by minimum of |x|, f1(q,y) = f2(q,y), hence f1(q,ya)=d(f1(q,y),a) = d(f2(q,y),a) = f2(q,ya), a contradiction.

Hence f1 = f2.

Languages accepted by DFAs

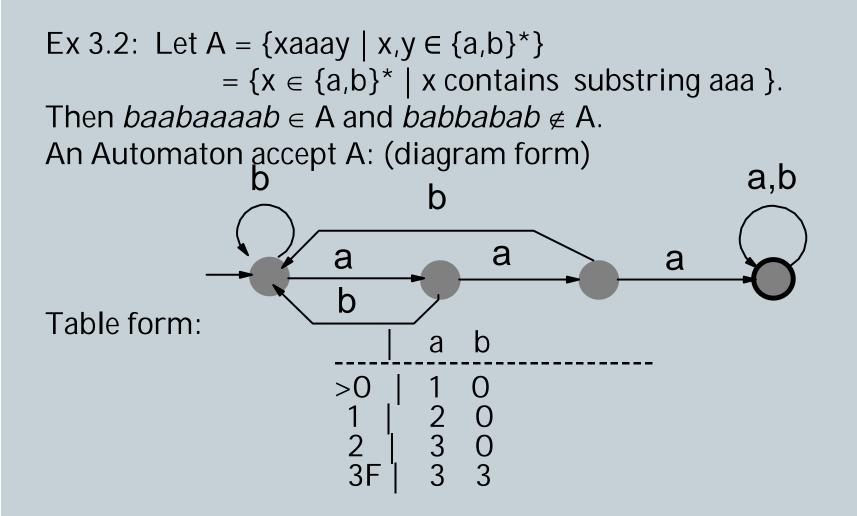
- M = (Q,S,d,s,F) : a DFA; x: any string over S;
 D: the extended transition function of M.
- x is said to be *accepted* by M if D(s,x) ∈ F
 x is said to be *rejected* by M if D(s,x) ∉ F.
- 2. The set (or language) accepted by M, denoted L(M), is the set of all strings accepted by M. i.e.,

• $L(M) =_{def} \{ x \in S^* \mid D(s,x) \in F \}.$

3. A subset $A \subseteq \Sigma^*$ (i.e., a language over S) is said to be *regular* if A is accepted by some finite automaton (i.e., A = L(M) for some DFA M).

Ex: The language accepted by the machine of Ex3.1 is the set $L(M1) = \{x \in \{a,b\}^* \mid x \text{ contains at least three } a's\}$

Another example



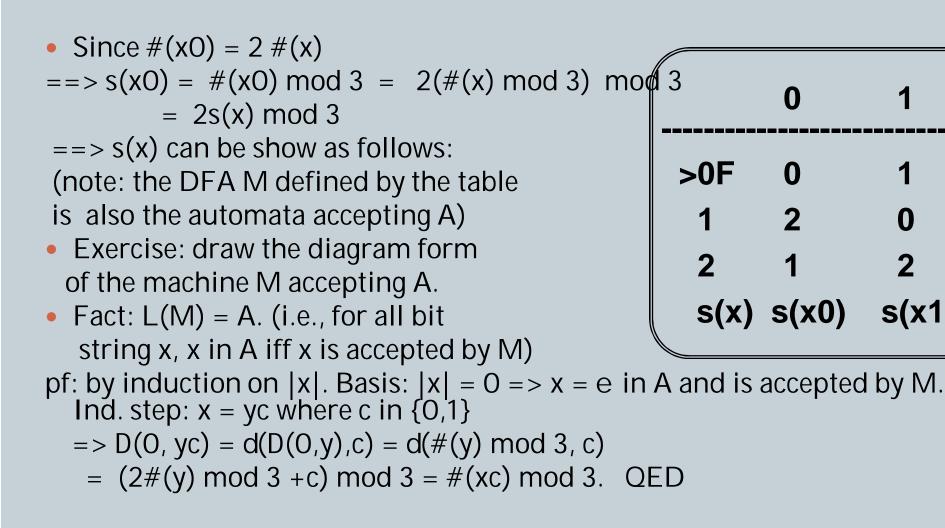
More on regular sets (Lecture 4)

- a little harder example:
 - Let $A = \{x \in \{0,1\}^* \mid x \text{ represent a multiple of 3 in binary}\}.$
 - notes: leading O's permitted; erepresents zero.
 - example:
 - e, 0, 00 ==> 0; 011,11,.. ==> 3; 110 ==> 6;
 - 1001 = > 9; 1100,... = > 12; 1111 = > 15; ...
- Problem: design a DFA accepting A.
- sol: For each bit string x, $s(x) = \#(x) \mod 3$, where #(x) is the number represented by x. Note: s: $\{0,1\}^* \rightarrow \{0,1,2\}$
 - Ex: s(e) = 0 mod 3 = 0; s(101) = 5 mod 3 = 2;...
 - ==> A = { x | S(x) = 0 }
 - 1. s(e) = 0;
 - s(x0) and s(x1) can be determined from s(x) as follows:

a little harder example

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s(x1)



Some closure properties of regular sets

Issue: what languages can be accepted by finite automata?

- Recall the definitions of some language operations:
 - $A \cup B = \{x \mid x \in A \text{ or } x \in B\}.$
 - $A \cap B = \{x \mid x \in A / \land x \in B\}$
 - $\circ \quad \sim A = S^* A = \{ x \in S^* \mid x \not\in A \}$
 - $AB = \{xy \mid x \in A \land y \in B\}$
 - $A^* = \{x_1 \ x_2 \ \dots x_n \mid n \ge 0 / \land x_i \in A \text{ for } 0 \le i \le n\}$
 - and more ... ex: $A / B = \{x \mid \$y \in B \text{ s.t. } xy \in A \}$.
- Problem: If A and B are regular [languages], then which of the above sets are regular as well?

Ans: _____.

The product construction

- $M_1 = (Q_1, S, d_1, s_1, F_1), M_2 = (Q_2, S, d_2, s_2, F_2)$: two DFAs Define a new machine $M_3 = (Q_3, S, d_3, s_3, F_3)$ where
 - $Q_3 = Q_1 \times Q_2 = \{(q_1, q_2) \mid q_1 \in Q_1 \text{ and } q_2 \in Q_2 \}$
 - $S_3 = (S_1, S_2);$
 - $F_3 = F_1 x F_2 = \{(q_1, q_2) \mid q_1 \in F_1 \land q_2 \in F_2\}$ and
 - d₃:Q₃ x S --> Q₃ is defined to be d₃((q₁,q₂), a) = (d₁(q₁,a), d₂(q₂,a)) for all (q₁,q₂)∈Q, a ∈ S.
- The machine M₃, denoted M₁xM₂, is called the *product* of M₁ and M₂. The behavior of M₃ may be viewed as the parallel execution of M₁ and M₂.
- Lem 4.1: For all $x \in S^*$, $D_3((p,q),x) = (D_1(p,x), D_2(q,x))$.

Pf: By induction on the length |x| of x.

Basis: |x| = 0: then $D_3((p,q),e) = (p,q) = (D_1(p,e), D_2(q,e))$

The product construction (cont'd)

Ind. step: assume the lemma hold for x in S^{*}, we show it holds for xa, where a in S.

- $D_{3}((p,q),xa) = d_{3}(D_{3}((p,q),x), a)$ = $d_{3}((D_{1}(p,x), D_{2}(q,x)), a)$ = $(d_{1}(D_{1}(p,x),a), d_{2}(D_{2}(q,x),a)$ = $(D_{1}(p,xa), D_{2}(p,xa))$ QED
- --- definition of D₃
- --- Ind. hyp.
- --- def. of d_3
- --- def of D_1 and D_2 .

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 \begin{array}{lll} \mbox{Theorem 4.2: } L(M_3) = L(M_1) \cap L(M_2). \\ \mbox{pf: for all } x \in S^*, x \in L(M_3) \\ \mbox{iff } D_3(s_3,x) \in F_3 & --- \mbox{ def. of acceptance} \\ \mbox{iff } D_3((s_1,s_2),x) \in F_3 & --- \mbox{ def. of } s_3 \\ \mbox{iff } (D_1(s_1,x), D_2(s_2,x)) \in F_3 = F_1xF2 & --- \mbox{ def. of } s_4 \\ \mbox{iff } D_1(s_1,x) \in F_1 \mbox{ and } D_2(s_2,x) \in F_2 & --- \mbox{ def. of set product} \\ \mbox{iff } x \in L(M_1) \mbox{ and } x \in L(M_2) & --- \mbox{ def. of intersection.} \\ \end{array}
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Regular languages are closed under U, \cap and ~

Theorem: IF A and B are regular than so are $A \cap B$, ~A and AUB. pf: (1) A and B are regular

=> \$ DFA M₁ and M₂ s.t. $L(M_1) = A$ and $L(M_2) = B$ -- def. of RL => $L(M_1xM_2) = L(M_1) \cap L(M_2) = A \cap B$ --- Theorem 4.2 ==> A ∩ B is regular. -- def. of RL. (2) Let M = (Q,S,d,s,F) be the machine s.t. L(M) = A. Define M' = (Q,S,d,s,F') where F' = ~F = {q ∈ Q | q ∉ F}. Now for all x in S^{*}, x ∈ L(M')

 $\langle = \rangle D(s,x) \in F' = \sim F$ --- def. of acceptance

 $\langle = \rangle D(s,x) \notin F$ --- def of $\sim F$ $\langle = \rangle x \notin L(M)$ iff $x \notin A$. -- def. of acceptance

Hence $\sim A$ is accepted by L(M') and is regular !

(3). Note that $AUB = \sim (\sim A \cap \sim B)$. Hence the fact that A and B are regular implies $\sim A$, $\sim B$, $(\sim A \cap \sim B)$ and $\sim (\sim A \cap \sim B) = AUB$ are regular too.